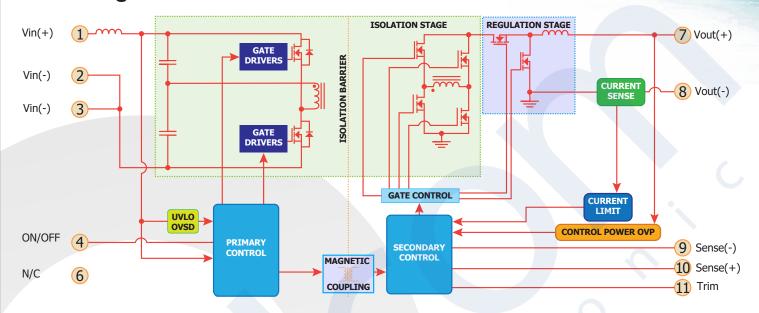


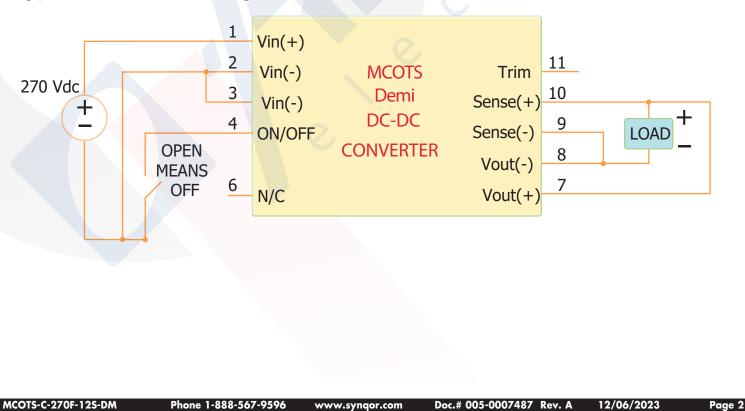


Singel 3 | B-2550 Kontich | Belgium | Tel. + 32 (0)3 458 30 33 | info@alcom.be | www.alcom.be Rivium 1e straat 52 | 2909 LE Capelle aan den Ijssel | The Netherlands | Tel. + 31 (0)10 288 25 00 | info@alcom.nl | www.alcom.nl

Block Diagram



Typical Connection Diagram



Current: 4 A

Electrical Characteristics MCOTS-C-270F-12S-DM ELECTRICAL CHARACTERISTICS

®

Tb = 25 °C, Vin = 270 Vdc, full load unless otherwise noted; full operating temperature range is -55 °C to +100 °C baseplate temperature with appropriate power derating. Specifications subject to change without notice.

| Parameter | Min. | Typ. | Max. | Units | Notes & Conditions |
|---|-------|------------|-------|--------|--|
| ABSOLUTE MAXIMUM RATINGS | · | | | | |
| Input Voltage | | | | | |
| Non-Operating | -1 | | 500 | V | Continuous |
| Operating | | | 300 | V | Continuous |
| Operating Transient Protection | | | 350 | V | 100 ms transient, square wave |
| Isolation Voltage | | | | | |
| Input to Output | | | 4250 | V | Reinforced Insulation |
| Input to Baseplate | | | 2300 | V | Basic Insulation |
| Output to Baseplate | | | 2300 | V | Basic Insulation |
| Operating Case Temperature | -55 | | 100 | °C | Baseplate temperature |
| Storage Case Temperature | -65 | | 135 | °C | |
| /oltage at ON/OFF input pin | -1.2 | | 50 | V | |
| INPUT CHARACTERISTICS | | | | | |
| Operating Input Voltage Range | 200 | 270 | 300 | V | 350 V transient for 100 ms; see Notes 1, 5 & 8 |
| Input Under-Voltage Turn-On Threshold | 189 | 193 | 197 | V | See Note 3 |
| Input Under-Voltage Turn-Off Threshold | 182 | 187 | 190 | V | See Note 3 |
| Input Under-Voltage Shutdown Hysteresis | 102 | 6.0 | 150 | V | |
| Input Over-Voltage Turn-Off Threshold | 312 | 315 | 320 | V | See Note 3 |
| Input Over-Voltage Turn-On Threshold | 300 | 307 | 310 | V | See Note 3 |
| Input Over-Voltage Shutdown Hysteresis | 500 | 8.0 | 510 | V | See note 5 |
| Recommended External Input Capacitance | | 4.7 | | μF | Typical ESR 8Ω see Note 8 |
| Input Filter Component Values (L\C) | | 4.7\0.7 | | μΗ\μF | Internal values; see Figure D |
| Maximum Input Current | | 4.7\0.7 | 0.33 | Α | Vin = 200 V; Iout = 4 A |
| | | 14 | 16 | mA | $VIII = 200 V_{1}^{2} 1001 = 4 A$ |
| No Load Input Current | | | | | |
| Disabled Input Current | | 2 | 5 | mA | Bandwidth 100 kl = 10 Ml = and Figure 17 |
| Input Terminal Current Ripple (rms) | | 20 | 10 | mA | Bandwidth = 100 kHz – 10 MHz; see Figure 17 |
| Recommended Input Fuse | | | 10 | A | Fast acting external fuse recommended |
| OUTPUT CHARACTERISTICS | 11.00 | 12.00 | 12.12 | V | Verit at capita lands |
| Output Voltage Set Point | 11.88 | 12.00 | 12.12 | | Vout at sense leads |
| Output Voltage Regulation | 0.0 | | 0.2 | mV | |
| Over Line | -0.3 | | 0.3 | % | |
| Over Load | -0.3 | | 0.3 | % | |
| Over Temperature | -180 | 12.00 | 180 | mV | |
| Total Output Voltage Range | 11.76 | 12.00 | 12.24 | V | Over sample, line, load, temperature & life |
| Output Voltage Ripple and Noise (Peak to Peak) | | 40 | 100 | mV | Bandwidth = 20 MHz; CL=11 µF |
| Output Voltage Ripple and Noise (rms) | | 15 | 30 | mV | Bandwidth = 20 MHz; CL=11 μ F |
| Operating Output Current Range | 0 | × | 4 | A | |
| Operating Output Power Range | 0 | | 50 | W | |
| Output DC Current-Limit Inception | 4.7 | 5.1 | 5.4 | A | |
| Back-Drive Current Limit while Enabled | | 1 | | А | |
| Back-Drive Current Limit while Disabled | | 10 | | mA | |
| Maximum Output Capacitance | | | 1500 | μF | |
| Output Voltage Deviation Load Transient | | | | | See Note 4 |
| For a Pos. Step Change in Load Current | | -700 | | mV | |
| Settling Time | | 400 | | μs | |
| Response to Input Transient | | 2900 | | mV | See Figure 12, see Note 5 |
| | 10 | | 10 | % | See Figure B |
| Output Voltage Trim Range | -10 | | | | |
| | 14.2 | 14.8 | 15.4 | V | |
| Output Voltage Trim Range | | 14.8 | 15.4 | V | |
| Output Voltage Trim Range Output Over-Voltage Shutdown | | 14.8 89 | 15.4 | V % | |

Current: 4 A

Electrical Characteristics MCOTS-C-270F-12S-DM ELECTRICAL CHARACTERISTICS (Continued)

Tb = 25 °C, Vin = 270 Vdc, full load unless otherwise noted; full operating temperature range is -55 °C to +100 °C baseplate temperature with appropriate power derating. Specifications subject to change without notice.

| Parameter | Min. | Тур. | Max. | Units | Notes & Conditions |
|---|------------|-------|------|----------|---|
| ISOLATION CHARACTERISTICS | | | | | |
| Isolation Voltage (dielectric strength) | | | | | See Absolute Maximum Ratings |
| Isolation Resistance | | 100 | | MΩ | |
| Isolation Capacitance (input to output) | | | NA | nF | See Note 7 |
| TEMPERATURE LIMITS FOR POWER DERAT | ING CURVES | | | | |
| Semiconductor Junction Temperature | | | 125 | °C | Package rated to 150 °C |
| Board Temperature | | | 125 | °C | UL rated max operating temp 130 °C |
| Transformer Temperature | | | 125 | °C | |
| Maximum Baseplate Temperature, Tb | | | 100 | °C | |
| FEATURE CHARACTERISTICS | | | | | |
| Switching Frequency | 395 | 400 | 407 | kHz | Isolation stage switching freq. is half this |
| ON/OFF Control | | | | | |
| Off-State Voltage | | | 0.8 | V | |
| Module Off Pulldown Current | 80 | | | μA | Current drain required to ensure module is off |
| On-State Voltage | 2 | | | V | |
| Module On Pin Leakage Current | | | 20 | μA | Imax draw from pin allowed with module still on |
| Pull-Up Voltage | 3.2 | 4.0 | 4.8 | V | See Figure A |
| DYNAMIC CHARACTERISTICS | | | | | |
| Turn-On Transient | | | | | 8 |
| Output Voltage Rise Time | | 130 | 160 | ms | Vout = 1.2 V to 10.8 V; Full Resistive Load |
| Output Voltage Overshoot | | 0 | 2 | % | Resistive load |
| Turn-On Delay, Rising Vin | | 35 | 50 | ms | On/Off = 5 V; see Notes 6 & 2 |
| Turn-On Delay, Rising ON/OFF | | 2.0 | 6.0 | ms | See Note 2 |
| Restart Inhibit Time | | 400 | | ms | See Note 2 |
| RELIABILITY CHARACTERISTICS | | | | | |
| Calculated MTBF per MIL-HDBK-217F | | 1.2 | | 106 Hrs. | Ground Benign, 70 °C Tb |
| Calculated MTBF per MIL-HDBK-217F | | 0.147 | | 106 Hrs. | Ground Mobile, 70 °C Tb |

Electrical Characteristics Notes

1. Converter will undergo input over-voltage shutdown.

2. After a disable or fault event, module is inhibited from restarting for 400 ms. See Shut Down section of the Control Features description.

3. High or low state of input voltage must persist for about 200 µs to be acted on by the shutdown circuitry.

4. Load current transition time \geq 10 µs.

5. Line voltage transition time \geq 100 µs.

6. Input voltage rise time \geq 250 µs.

7. Isolation capacitance can be added external to the module.

8. An input capacitor with series resistance is necessary to provide system stability.

Current: 4 A

Technical Charts

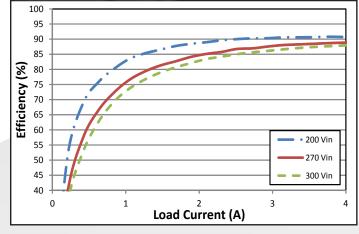
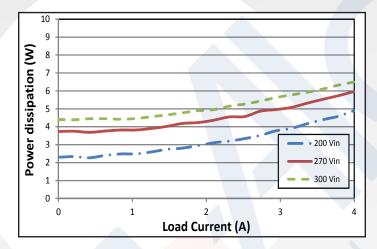
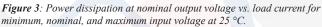


Figure 1: Efficiency at nominal output voltage vs. load current for minimum, nominal, and maximum input voltage at 25 °C.





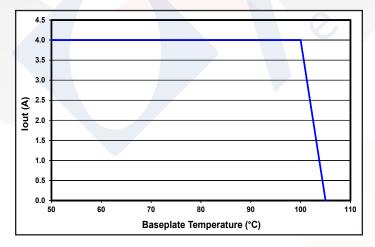


Figure 5: Maximum output current vs. baseplate temperature (nominal input voltage.)

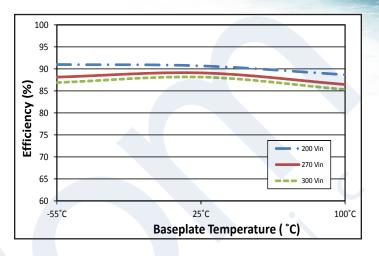


Figure 2: Efficiency at nominal output voltage and 100% rated power vs. case temperature for minimum, nominal, and maximum input voltage.

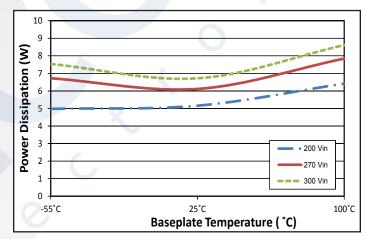


Figure 4: Power dissipation at nominal output voltage and 100% rated power vs. case temperature for minimum, nominal, and maximum input voltage

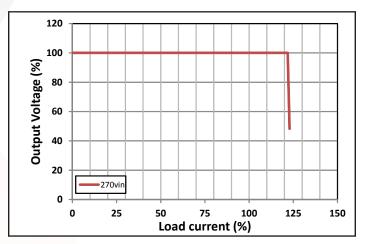


Figure 6: Output voltage vs. load current showing typical current limit curves. See Current limit section in application notes.

Technical Charts

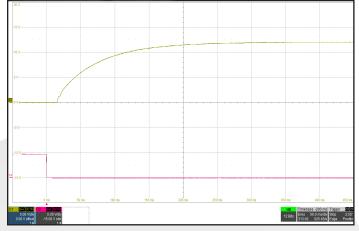


Figure 7: Turn-on transient at no load and zero output capacitance initiated by On/Off. Input voltage pre-applied. Ch 1: Vout (5 V/div). Ch 2: On/Off (5 V/div). Timecale: 50.0ms/div.

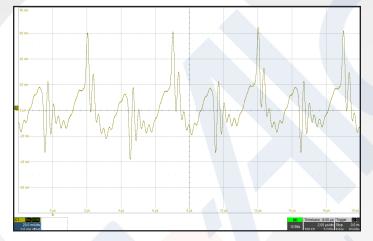
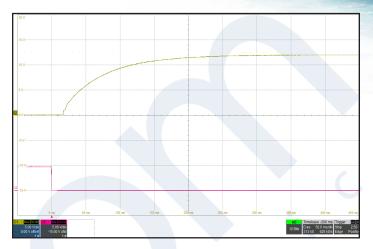
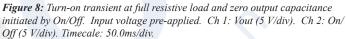


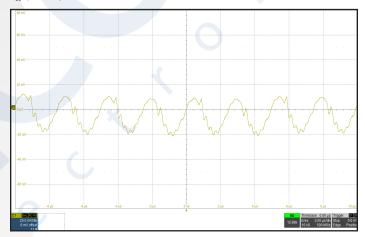
Figure 9: Input terminal current ripple, at full rated output current and nominal input voltage (20 mA/div). Timescale: 2.00µs/div. See Figure 17.

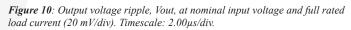


Figure 11: Output voltage response to step-change in load current 50%-100%-50% of lout (max).No external load capacitance. Ch 1: Vout (500 mV/div.) Ch 2: lout (2 A/div). Timescale: 200µs/div.









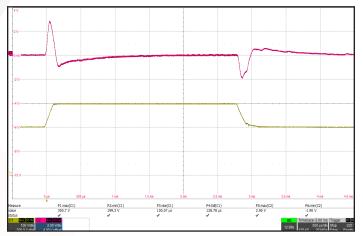


Figure 12: Output voltage response to step-change in input voltage (200 V - 300 V - 200 V) in 100 µS. Ch 2: Vout (2 V/div). Ch 1: Vin (100 V/div). Timescale: 500µs/div.

Technical Charts

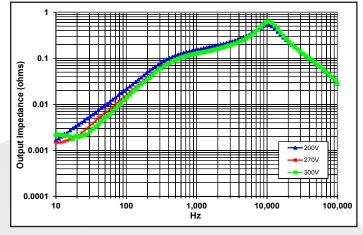


Figure 13:Magnitude of incremental output impedance $(Z_{out} = v_{oul}/i_{out})$ for minimum, nominal, and maximum input voltage at full rated power.

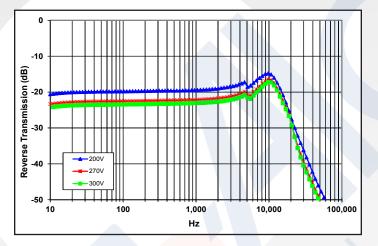
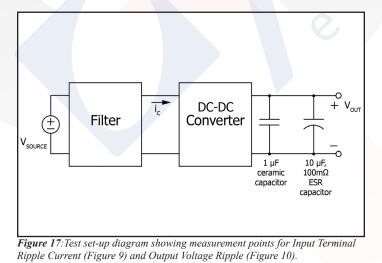


Figure 15: Magnitude of incremental reverse transmission ($RT = i_u i_{out}$) for minimum, nominal, and maximum input voltage at full rated power.



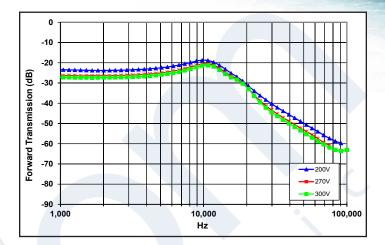


Figure 14: Magnitude of incremental forward transmission ($FT = v_{oul}/v_{in}$) for minimum, nominal, and maximum input voltage at full rated power.

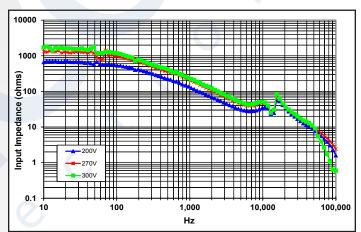


Figure 16: Magnitude of incremental input impedance $(Z_{in} = v_{in} i_{in})$ for minimum, nominal, and maximum input voltage at full rated power.

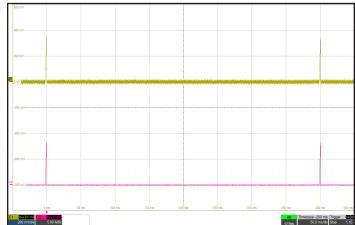


Figure 18: A short circuit across the output terminals. Ch 1: Vout (200 mV/div). Ch 2: Iout (5 A/div).

Phone 1-888-567-9596

Page 7

Application Section BASIC OPERATION AND FEATURES

The MCOTS DC-DC converter uses a two-stage power conversion topology. The first, or isolation, stage uses a transformer to provide the functions of input/output isolation and voltage transformation to achieve the required output voltage. The second, or regulation, stage is a buck-converter that keeps the output voltage constant over variations in line, load, and temperature.

Both the regulation and the isolation stages switch at a fixed frequency for predictable EMI performance. The isolation stage switches at one half the frequency of the regulation stage, but due to the push-pull nature of this stage it creates a ripple at double its switching frequency. As a result, both the input and the output of the converter have a fundamental ripple frequency of about 400 kHz.

Rectification of the isolation stage's output is accomplished with synchronous rectifiers. These devices, which are MOSFETs with a very low resistance, dissipate far less energy than would Schottky diodes. This is the primary reason why the MCOTS converters have such high efficiency, particularly at low output voltages.

Besides improving efficiency, the synchronous rectifiers permit operation down to zero load current. There is no longer a need for a minimum load, as is typical for converters that use diodes for rectification. The synchronous rectifiers actually permit a negative load current to flow back into the converter's output terminals if the load is a source of short or long term energy. The MCOTS converters employ a "back-drive current limit" to keep this negative output terminal current small.

There is a control circuit in the MCOTS converter that determines the conduction state of the power switches. It communicates across the isolation barrier through a magnetically coupled device. No opto-isolators are used.

An input under-voltage shutdown feature with hysteresis is provided, as well as an input over-voltage shutdown and an output over-voltage limit. There is also an output current limit that is nearly constant as the load impedance decreases (i.e., there is not foldback or fold-forward characteristic to the output current under this condition). When a load fault is removed, the output voltage rises exponentially to its nominal value without an overshoot.

The following sections describe the use and operation of additional control features provided by the MCOTS converter.

CONTROL FEATURES

Remote ON/OFF: The MCOTS converter has one on/off function pin, ON/OFF (pin 4), which is referenced with respect to the converter's Vin(-) (pin 2). It must have a logic low level for the converter to be enabled; a logic high inhibits the converter.

The ON/OFF pin is internally pulled high so that an open connection will inhibit the converter. Figure A shows the equivalent circuit looking into the ON/OFF pin. It is TTL compatible and has hysteresis.

SHUTDOWN: The MCOTS converter will shut down in response to only six conditions: ON/OFF input high, Vin input below under-

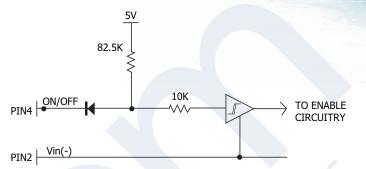


Figure A: Circuit diagram shown for reference only, actual circuit components may differ from values shown for equivalent circuit.

voltage shutdown threshold, Vin input above over-voltage shutdown threshold, over-temperature shutdown threshold, output voltage above the output over-voltage threshold and persistent current limit event lasting more than 20 ms. Following any shutdown event, there is a startup inhibit delay which will prevent the converter from restarting for approximately 400 ms. After the 400 ms delay elapses, if the ON/OFF input is low and the input voltage is within the operating range, the converter will restart. If the Vin input is brought down to nearly 0 V and back into the operating range, there is no startup inhibit, and the output voltage will rise according to the "Turn-On Delay, Rising Vin" specification.

REMOTE SENSE: The purpose of the remote sense pins is to correct for the voltage drop along the conductors that connect the converter's output to the load. To achieve this goal, a separate conductor should be used to connect the Sense(+) pin (pin 10) directly to the positive terminal of the load, as shown in the connection diagram on Page 2. Similarly, the Sense(-) pin (pin 9) should be connected through a separate conductor to the return terminal of the load.

NOTE: Even if remote sensing of the load voltage is not desired, the Sense(+) and the Sense(-) pins must be connected to Vout(+) (pin 7) and Vout(-) (pin 8), respectively, to get proper regulation of the converter's output. If they are left open, the converter will have an output voltage that is approximately 200 mV higher than its specified value.

Inside the converter, Sense(+) is connected to Vout(+) with a 100 Ω resistor and Sense(-) is connected to Vout(-) with a 10 Ω resistor.

It is also important to note that when remote sense is used, the voltage across the converter's output terminals (pins 7 and 8) will be higher than the converter's nominal output voltage due to resistive drops along the connecting wires. This higher voltage at the terminals produces a greater voltage stress on the converter's internal components. It may cause the converter to fail to deliver the desired output voltage at the low end of the input voltage range and at the higher end of the load current & temperature range. Please consult the factory for details.



Application Section

OUTPUT VOLTAGE TRIM: The Trim pin (pin 11) can adjust the MCOTS converter's output voltage $\pm 10\%$ around its nominal value.

To trim the output voltage above its nominal value, connect an external resistor from the Trim pin to the Sense(+) pin as shown in Figure C. The value of this trim up resistor should be chosen according to the following equation or from Figure B:

 $R_{trim-up} = \frac{5.11 \text{Vout x (100+}\Delta\%)}{1.225\Delta\%} - \frac{511}{\Delta\%} - 10.22 \text{ (k}\Omega)$

where:

$$\Delta\% = \left| \frac{\text{Vnominal} - \text{Vdesired}}{\text{Vnominal}} \right| \ge 100\%$$

V_{out} = Nominal Output Voltage

As the output voltage is trimmed up, it produces a greater voltage stress on the converter's internal components. It may cause the converter to fail to deliver the desired output voltage at the low end of the input voltage range and at the higher end of the load current & temperature range. Please consult the factory for details. To trim the output voltage below its nominal value, connect an external resistor between the Trim pin and the Sense(-) pin. The value of this trim down resistor should be chosen according to the following equation or from Figure B:

$$R_{trim-down} = \frac{511}{\Delta\%} - 10.22 \ (k\Omega)$$

INPUT UNDER-VOLTAGE SHUTDOWN: The MCOTS converter has an under-voltage shutdown feature that ensures the converter will be off if the input voltage is too low. The input voltage turnon threshold is higher than the turn-off threshold. In addition, the MCOTS converter will not respond to a state of the input voltage unless it has remained in that state for more than about 200µs. This hysteresis and the delay ensure proper operation when the source impedance is high or in a noisy environment.

INPUT OVER-VOLTAGE SHUTDOWN: The MCOTS converter also has an over-voltage feature that ensures the converter will be off if the input voltage is too high. It also has a hysteresis and time delay to ensure proper operation.

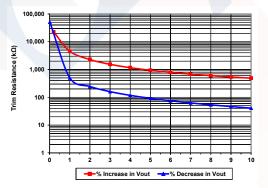


Figure B: Trim up and Trim down as a function of external trim resistance.

Page 9

OUTPUT OVER-VOLTAGE SHUTDOWN: The MCOTS converter will shut down if the voltage at its power output pins ever exceeds about 125% of the nominal value. The shutdown threshold does not change with output trim or sense drops; excessive trim-up or output wiring drops may cause an output over-voltage shutdown event. After a startup inhibit delay, the converter will attempt to restart.

OVER-TEMPERATURE SHUTDOWN: A temperature sensor on the converter senses the average temperature of the module. The thermal shutdown circuit is designed to turn the converter off when the temperature at the sensed location reaches the Over-Temperature Shutdown value. It will allow the converter to turn on again when the temperature of the sensed location falls by the amount of the Over-Temperature Shutdown Restart Hysteresis value.

BACK-DRIVE CURRENT LIMIT: Converters that use MOSFETs as synchronous rectifiers are capable of drawing a negative current from the load if the load is a source of short- or long-term energy. This negative current is referred to as a "back-drive current".

Conditions where back-drive current might occur include paralleled converters that do not employ current sharing. It can also occur when converters having different output voltages are connected together through either explicit or parasitic diodes that, while normally off, become conductive during startup or shutdown. Finally, some loads, such as motors, can return energy to their power rail. Even a load capacitor is a source of back-drive energy for some period of time during a shutdown transient.

To avoid any problems that might arise due to back-drive current, the MCOTS converters limit the negative current that the converter can draw from its output terminals. The threshold for this back-drive current limit is placed sufficiently below zero so that the converter may operate properly down to zero load, but its absolute value (see the Electrical Characteristics page) is small compared to the converter's rated output current.

CURRENT LIMIT: In the event of excess load, the MCOTS converter will quickly reduce its output voltage to keep the load current within safe limits (see Figure 6). If the overload persists for more than 20 ms, the converter will shut off, wait a restart delay, and then automatically attempt to re-start. The timeout is internally implemented with an integrator: counting up whenever current limit is active, and counting down at 1/5th the rate whenever current limit becomes inactive. In this way a series of short-duration overloads will not cause the converter to shut down, while it will shut down in response to sustained overloads.

Current: 4 A

Application Section

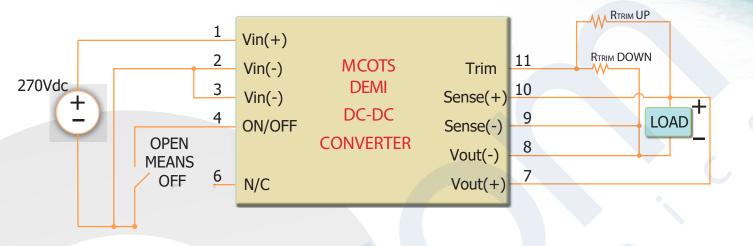
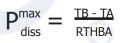


Figure C: Typical connection for output voltage trimming.

INPUT SYSTEM INSTABILITY: This condition can occur because any dc-dc converter appears incrementally as a negative resistance load. A detailed application note titled "Input System Instability" is available on the SynQor website which provides an understanding of why this instability arises, and shows the preferred solution for correcting it.

THERMAL CONSIDERATIONS: The maximum operating baseplate temperature, TB, is 100 °C. Refer to the thermal derating curve, Figure 5, to see the available output current at baseplate temperatures below 100 °C.

A power derating curve can be calculated for any heatsink that is attached to the base-plate of the converter. It is only necessary to determine the thermal resistance, RTHBA, of the chosen heatsink between the base-plate and the ambient air for a given airflow rate. This information is usually available from the heatsink vendor. The following formula can then be used to determine the maximum power the converter can dissipate for a given thermal condition:



This value of power dissipation can then be used in conjunction with the data shown in Figure 3 to determine the maximum load current (and power) that the converter can deliver in the given thermal condition.

INPUT FILTERING AND EXTERNAL CAPACITANCE: Figure D provides a diagram showing the internal input filter components. This filter dramatically reduces input terminal ripple current, which otherwise could exceed the rating of the converter's external electrolytic input capacitor. More detailed information is available in the application note titled "EMI Characteristics" on the SynQor website.

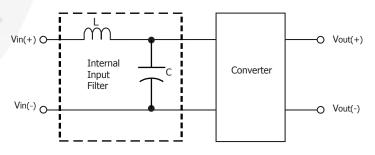
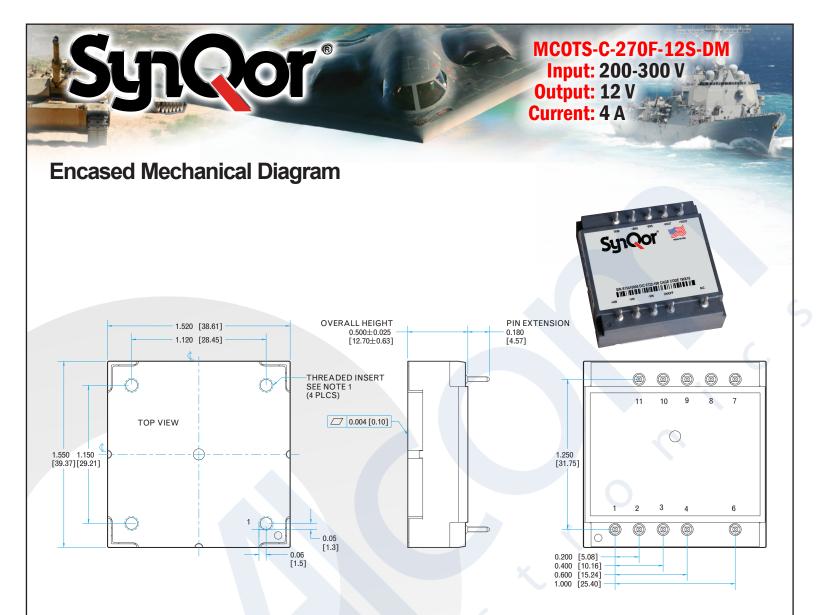


Figure D: Diagram showing the internal input filter components.



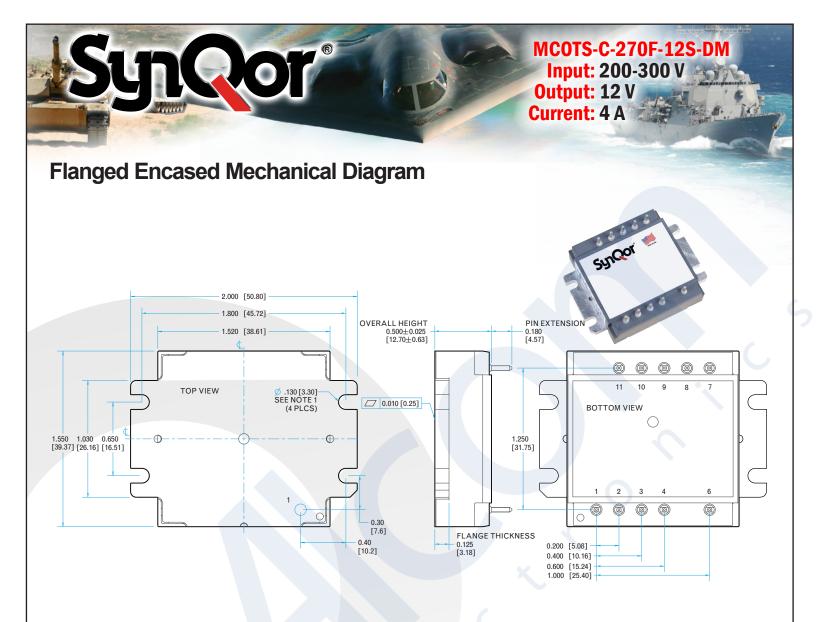
NOTES:

- 1: APPLIED TORQUE PER M3 SCREW 6 in-lb (0.7 Nm) RECOMMENDED. SCREW SHOULD NOT EXCEED 0.100" (2.54 mm) DEPTH BELOW THE SURFACE OF THE BASEPLATE.
- 2: BASEPLATE FLATNESS TOLERANCE IS 0.004" (.10 mm) TIR FOR SURFACE.
- 3: PINS 1-4, 6-11 ARE .040" (1.02 mm) DIA, WITH 0.080" (2.03 mm) DIA. STANDOFF
- 4: ALL PINS: MATERIAL: COPPER ALLOY FINISH: MATTE TIN OVER NICKEL PLATE
- 5: WEIGHT: 1.97 oz. (56 g)
- 6: ALL DIMENSIONS IN INCHES(mm) TOLERANCES: X.XXIN +/-0.02 (X.X mm +/-0.5 mm) X.XXXIN +/-0.010 (X.XX mm +/-0.25 mm)

PIN DESIGNATIONS Pin # Label Name Function 1 +VIN Vin(+) Positive input voltage 2 -VIN Vin(-) Input return 3 -VIN Vin(–) Input return 4 ON/OFF ON/OFF | Turns converter on and off 6 N/C N/C No connection 7 Positive output voltage +VOUT Vout(+) 8 -VOUT Vout(-) Output return 9 - SNS Sense(-) Negative remote sense + SNS 10 Sense(+) Positive remote sense TRIM Trim Output voltage trim 11

Pin Designation Notes:

1: Pin out differs from other Mil-COTS products.



NOTES:

- 1: APPLIED TORQUE PER M3 OR 4-40 SCREW 6 in-lb (0.7 Nm) RECOMMENDED.
- 2: BASEPLATE FLATNESS TOLERANCE IS 0.010" (.25 mm) TIR FOR SURFACE.
- 3: PINS 1-4, 6-11 ARE .040" (1.02 mm) DIA, WITH 0.080" (2.03 mm) DIA. STANDOFF
- 4: ALL PINS: MATERIAL: COPPER ALLOY FINISH: MATTE TIN OVER NICKEL PLATE

5: WEIGHT: 2.08 oz. (59 g) ALL DIMENSIONS IN INCHES(mm)

6: TOLERANCES: X.XXIN +/-0.02 (X.X mm +/-0.5 mm) X.XXXIN +/-0.010 (X.XX mm +/-0.25 mm)

PIN DESIGNATIONS

| Pin | # | Label | Name | Function |
|-----|---|--------|----------|----------------------------|
| 1 | 9 | +VIN | Vin(+) | Positive input voltage |
| 2 | | -VIN | Vin(–) | Input return |
| 3 | | -VIN | Vin(–) | Input return |
| 4 | | ON/OFF | ON/OFF | Turns converter on and off |
| 6 | | N/C | N/C | No connection |
| 7 | | +VOUT | Vout(+) | Positive output voltage |
| 8 | | -VOUT | Vout(-) | Output return |
| 9 | | - SNS | Sense(–) | Negative remote sense |
| 10 |) | + SNS | Sense(+) | Positive remote sense |
| 11 | | TRIM | Trim | Output voltage trim |

Pin Designation Notes:

1: Pin out differs from other Mil-COTS products.

Qualifications & Screening

| MII-COTS Qualification | | | | | | | |
|------------------------|--|------------------------|--|--|--|--|--|
| Test Name | Details | # Tested (# Failed) | Consistent with MIL-STD-883F Method | | | | |
| Life Testing | Visual, mechanical and electrical testing before, during and after 1000 hour burn-in @ full load | 15 (0) | Method 1005.8 | | | | |
| Shock- Vibration | Visual, mechanical and electrical testing before, during and after shock and vibration tests | 5 (0) | MIL-STD-202, Methods 201A & 213B | | | | |
| Humidity | +85 °C, 95% RH, 1000 hours, 2 minutes on / 6 hours off | 8 (0) | Method 1004.7 | | | | |
| Temperature Cycling | 500 cycles of -55 °C to +100 °C (30 minute dwell at each temperature) | 10 (0) | Method 1010.8, Condition A | | | | |
| Solderability | 15 pins | 15 (0) | Method 2003 | | | | |
| DMT | -65 °C to +110 °C across full line and load specifications in 5 °C steps | 7 (0) | | | | | |
| Altitude | 70,000 feet (21 km), see Note | 2 (0) | | | | | |

COTC Ourslifestion

®

Note: A conductive cooling design is generally needed for high altitude applications because of naturally poor convective cooling at rare atmospheres.

Mil-COTS Converter and Filter Screening

| Screening | Process Description | S-Grade | M-Grade | |
|---------------------------------|--|-------------------|-------------------------|--|
| Baseplate Operating Temperature | | -55 °C to +100 °C | -55 °C to +100 °C | |
| Storage Temperature | | -65 °C to +135 °C | -65 °C to +135 °C | |
| Pre-Cap Inspection | IPC-A-610, Class III | • | • | |
| Temperature Cycling | MIL-STD-883F, Method 1010, Condition B, 10 Cycles | | • | |
| Burn-In | 100 °C Baseplate | 12 Hours | 96 Hours | |
| Final Electrical Test | 100% | 25 °C | -55 °C, +25 °C, +100 °C | |
| Final Visual Inspection | MIL-STD-883F, Method 2009 | | • | |

Mil-COTS MIL-STD-810G Qualification Testing

| MIL-STD-810G Test | Method | Description | | | | |
|---|-----------------------|--|--|--|--|--|
| Fungus | 508.6 | Table 508.6-I | | | | |
| Altitude | 500.5 - Procedure I | Storage: 70,000 ft / 2 hr duration | | | | |
| Altitude | 500.5 - Procedure II | Operating: 70,000 ft / 2 hr duration; Ambient Temperature | | | | |
| Rapid Decompression | 500.5 - Procedure III | Storage: 8,000 ft to 40,000 ft | | | | |
| Acceleration | 513.6 - Procedure II | Operating: 15 g | | | | |
| Salt Fog | 509.5 | Storage | | | | |
| High Townsentrus | 501.5 - Procedure I | Storage: 135 °C / 3 hrs | | | | |
| High Temperature | 501.5 - Procedure II | Operating: 100 °C / 3 hrs | | | | |
| | 502.5 - Procedure I | Storage: -65 °C / 4 hrs | | | | |
| Low Temperature | 502.5 - Procedure II | Operating: -55 °C / 3 hrs | | | | |
| Temperature Shock 503.5 - Procedure I - C | | Storage: -65 °C to 135 °C; 12 cycles | | | | |
| Rain | 506.5 - Procedure I | Wind Blown Rain | | | | |
| Immersion | 512.5 - Procedure I | Non-Operating | | | | |
| Humidity | 507.5 - Procedure II | Aggravated cycle @ 95% RH (Figure 507.5-7 aggravated temp - humidity cycle, 15 cycles) | | | | |
| Random Vibration | 514.6 - Procedure I | 10 - 2000 Hz, PSD level of 1.5 g^2/Hz (54.6 g_{rms}), duration = 1 hr/axis | | | | |
| Charle | 516.6 - Procedure I | 20 g peak, 11 ms, Functional Shock (Operating no load) (saw tooth) | | | | |
| Shock | 516.6 - Procedure VI | Bench Handling Shock | | | | |
| Sinusoidal vibration | 514.6 - Category 14 | Rotary wing aircraft - helicopter, 4 hrs/axis, 20 g (sine sweep from 10 - 500 Hz) | | | | |
| Sand and Dust | 510.5 - Procedure I | Blowing Dust | | | | |
| Sanu anu Dust | 510.5 - Procedure II | Blowing Sand | | | | |

Phone 1-888-567-9596 www.synqor.com Doc.# 005-0007487 Rev. A 12/06/2023

Ordering Information

| | Part Numbering Scheme | | | | | | | |
|----------------|-----------------------|-------------------------------|-------------------|---------------|----------------------------------|--------------------------|----------------------|--|
| Family | Product | Input Voltage | Output Voltage | Package Size | Heatsink Option | Screening Level | Options | |
| | MCOTS C: Converter | nverter 270F: 200-300V | 3R3S: 3.3V Single | DM: Demi Mega | N: Normal Threaded F: Flanged | S: S-Grade M: M-Grade | []: Standard Feature | |
| MCOTS | | | 05S: 5.0V Single | | | | | |
| MCOTS C: Conve | C: Converter | | 12S: 12V Single | | | | | |
| | | | 28S: 28V Single | | | | | |

Ordering Information / Part Numbering

Example: MCOTS-C-270F-12S-DM-N-S Not all combinations make valid part numbers, please contact SynQor for availability.

Application Notes

A variety of application notes and technical white papers can be downloaded in pdf format from our website.

STANDARDS COMPLIANCE Parameter

STANDARDS COMPLIANCE

UL 62368-1 CAN/CSA-C22.2 No. 62368-1 Reinforced Insulation Input to Output

Notes & Conditions

EN 62368-1

Note: An external input fuse must always be used to meet these safety requirements. Contact SynQor for official safety certificates on new releases or download from the SynQor website.

Alcom Singel 3 | B-2550 Kontich | Belgium | Tel. +32 (0)3 458 30 33 | info@alcom.be | www.alcom.be Rivium 1e straat 52 | 2909 LE Capelle aan den Ijssel | The Netherlands | Tel. + 31 (0)10 288 25 00 | info@alcom.nl | www.alcom.nl

Contact SynQor for further information and to order:

Phone: 978-849-0600 Toll Free: 888-567-9596 Fax: 978-849-0602 Web: www.synqor.com E-mail: power@syngor.com Address: 155 Swanson Road, Boxborough, MA 01719 USA

WARRANTY

SynQor offers a two (2) year limited warranty. Complete warranty information is listed on our website or is available upon request from SynQor.

PATENTS

SynOor holds numerous U.S. patents, one or more of which apply to most of its power conversion products. Any that apply to the product(s) listed in this document are identified by markings on the product(s) or on internal components of the product(s) in accordance with U.S. patent laws. SynQor's patents include the following:

7,050,309 7,765,687 7,787,261 8,149,597 8,644,027