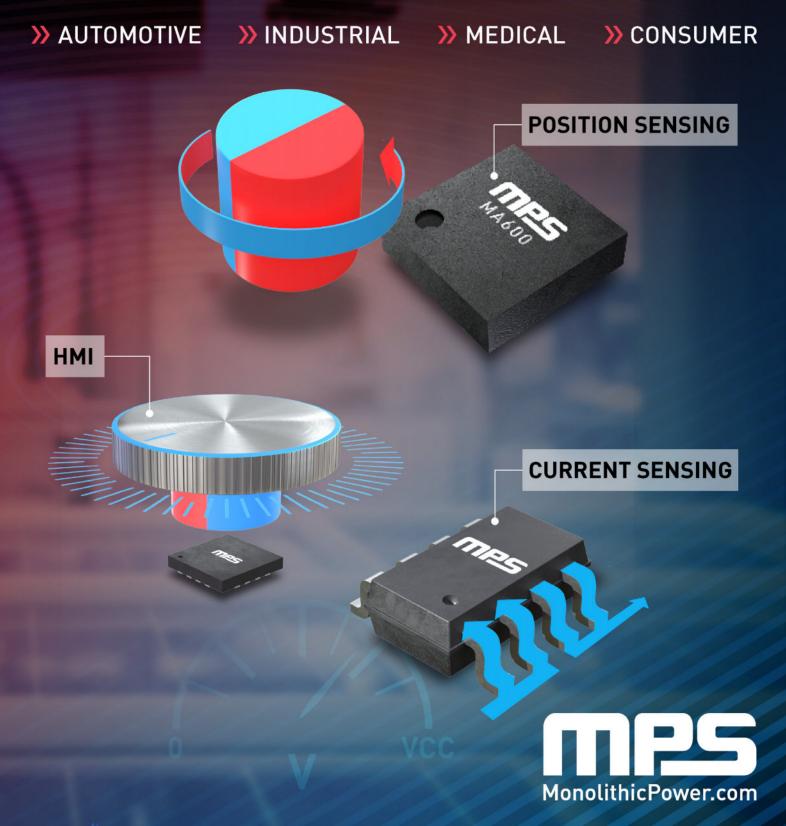
V. 12/23

# SENSOR SOLUTIONS

# **Designed for Applications In:**



Acom Singel 3 B-2550 Kontich | Belgium | Tel. +32 (0)3 458 30 33 | info@alcom be | www.alcom be Rivium 1e straat 52 | 2909 LF Capelle aan den lissel | The Netherlands | Tel. +31 (0)10 288 25 00 | info@alcom.nl | www.alcom

# **Quality Assurance & Reliability Commitment**

The MPS Quality Assurance organization develops, coordinates, and champions strategic quality initiatives throughout MPS Inc., its foundries, and subcontractors. Its mission is to enable MPS to design, develop, manufacture, and deliver products to our customers with world-class quality and reliability that meet and exceed our customers' expectations.

#### MPS and Its Supplier Quality Systems and Certificates:

- IS09001:2008 (MPS)
- EU RoHS/HF/REACH Compliant (MPS)
- Sony Green Partner (MPS & Suppliers)
- TS16949 (Suppliers)
- ISO14001 (Suppliers)
- Current Sensor UL Certification # CA-11398-UL c Sus

#### **Product Quality:**

- Automotive Products Qualified per AEC-Q100 Standard
- Standard Products Qualified per JEDEC and Military Standards
- Reliability Failure Rate <10FIT
- Product Quality Level <1.0ppm

#### **Quality Control and Monitoring:**

- On-Site Foundry and Assembly Teams for Real-Time Actions
- Quarterly Supplier Quality Review and Annual Supplier Audit
- Short-Term Reliability Monitor Test Daily
- Long-Term Reliability Monitor Test Monthly
- Real-Time Engineering Actions on Monitor Failure
- Quarterly Reliability Monitor Reports



# In This Guide

Product Overview	
MagAlpha Position Sensors	4
Current Sensors	5
Automotive	
Sensors for Motor Position/Speed Control and Current Sensors	6
Body Electronics	8
Power Management	8
Thermal Management	9
Interior Cabin Control and Car Audio	9
Power Steering	10
Automotive Product Selector Guide	11
Industrial Building & Factory Automation	
Safety & Security	12
Power Management	13
Thermal Management	13
Climate & Energy Efficiency	14
Industrial Automation	15
Medical Technology	
Lab Automation	16
Surgical Robotics	17
Automated Motorized Equipment	18
Consumer Products	
Mobile Phones & Laptop Computers	19
Battery-Powered Hand Tools	20
	21
Comprehensive Product Selector Guide	
Coreless Integrated Current Sensors	22
Position Sensor Magnets	23
MagVector <sup>™</sup> 3D Magnetic Position Sensors	23
MagAlpha™ Magnetic Position Sensors	24
Contact & Ordering	
About Monolithic Power Systems	26

# MagAlpha Position Sensors

#### Advantages of MagAlpha Angle Sensors:

- » Instantaneous, Absolute Angle Sensing
- » High Resolution
- » Low INL as Low as 0.5° (0.1°) over Temp and Reflow
- » High Bandwidth Up to 21kHz
- » Factory Calibration Eliminates In-System Calibration
- » Ideal for Battery-Powered Applications: <0.5µA Idle Current
- » Smallest Footprint: UTQFN-14 (2mmx2mmx0.6mm)
- » Flexible Sensor Location: End-of-Shaft (On-Axis) or Side-Shaft (Off-Axis)

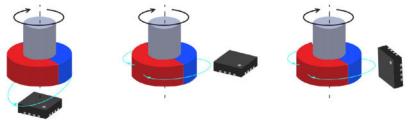
MagAlpha sensors utilize an array of Hall plates that are sampled successively at very high speeds in such a way that the signal phase represents the angle to be measured. The "phase-to-digital" SpinAxis<sup>™</sup> technique captures the angle instantaneously every 1µs without the need for traditional analog-to-digital conversion or arc tangent calculation. This means that the sensor is able to operate across a wider magnetic field range (typically 30mT to 150mT), giving greater flexibility and tolerance for magnet positioning.

The fast Hall sampling and subsequent digital conditioning result in very low latency, from Hall array sampling to the data availability at the sensor output. The typical latency is between 1µs to 8µs at a constant rotation speed, depending on the part number, allowing MagAlpha sensors to operate in systems with high rotation speeds, or in systems that require fast position control loops. Rotation speeds from 0rpm to more than 100,000rpm are possible.

#### Side-Shaft Capability

MagAlpha sensors support both end-of-shaft and side-of-shaft topologies. In end-of-shaft, the sensor is placed directly below the magnet connected to the rotating shaft. This topology offers the best performance, but is not always mechanically convenient because the end of a rotating shaft may not be accessible. For example, in a motor, it may be hidden by the shaft bearing, or driving into a gearbox.

Side-shaft topology allows the magnet to be placed to the side of a ring magnet, mounted on the rotating shaft. This is advantageous for many designs, as the ring can be located anywhere on the shaft, which allows the sensor to be embedded more easily within the motor or product casing. MagAlpha sensors include dedicated bias trimming registers for side-shaft applications. When the sensor is placed in a side-shaft configuration, the unique bias trimming enables the sensor to measure irregular magnetic fields and output a linear response across the full angle range without in-system calibration (see **Figure 1**).



End-of-Shaft Mode

Side-Shaft Mode Orthogonal Side-Shaft Mode

#### Figure 1: Magnet and Sensor Positioning

# **Current Sensors**

#### Advantages of MPS Current Sensors:

- » Complete Isolated Current Sensor in a Small SOIC-8 (5mmx6.2mm) Package
- » Single IC Is Simple and Cost-Effective to Design In
- » Ultra-Small QFN-12 (3mmx3mm) for Non-Isolated Applications
- » Wide Current-Sensing Range from ±5A to ±50A, AC or DC
- » Low Conductor Resistance for Low Power Loss:  $0.9 m \Omega$
- » ±2.5% Accuracy over Temp, Factory-Trimmed
- » Immune to Stray Magnetic Fields via Differential Sensing
- » No Magnetic Hysteresis

MPS current sensors integrate galvanic isolation, high-voltage continuous operation, and highcurrent sensing into a small, industry-standard SOIC-8 package. Our current sensors utilize an array of differential, linear Hall sensors that pick up the target induced magnetic field from the primary conductor while rejecting unwanted stray fields. This makes our current sensors ideal for use in magnetically noisy environments. In addition, the low resistance of the integrated conductor results in improved efficiency and reduced power loss compared to a traditional shunt resistor solution.

The low-resistance primary conductor allows current to flow near the sensor IC. The current generates a magnetic field, which is sensed at two different points by the integrated Hall sensors. The magnetic field difference between these two points is converted into a ratiometric voltage proportional to the applied current (see **Figure 2**). MPS's unique spinning current technique provides a low offset that remains stable across a wide temperature range.

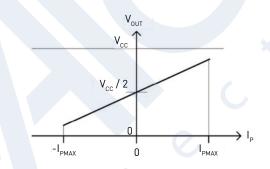


Figure 2: Output Voltage Proportional to Primary Current

The primary conducting leads are electrically isolated from the sensor leads on the secondary side, producing a sensor with a high isolation voltage and working voltage (see **Figure 3**). This makes our current sensors ideal for high-side current sensing without the need for expensive, large-footprint optical or inductive isolation alternatives.

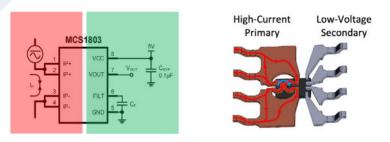
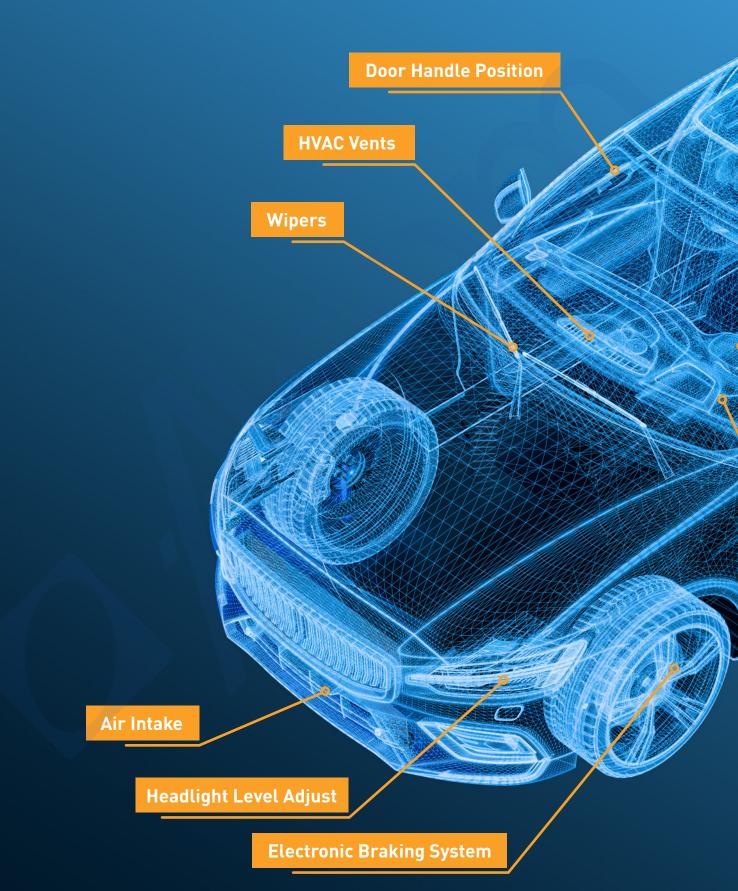


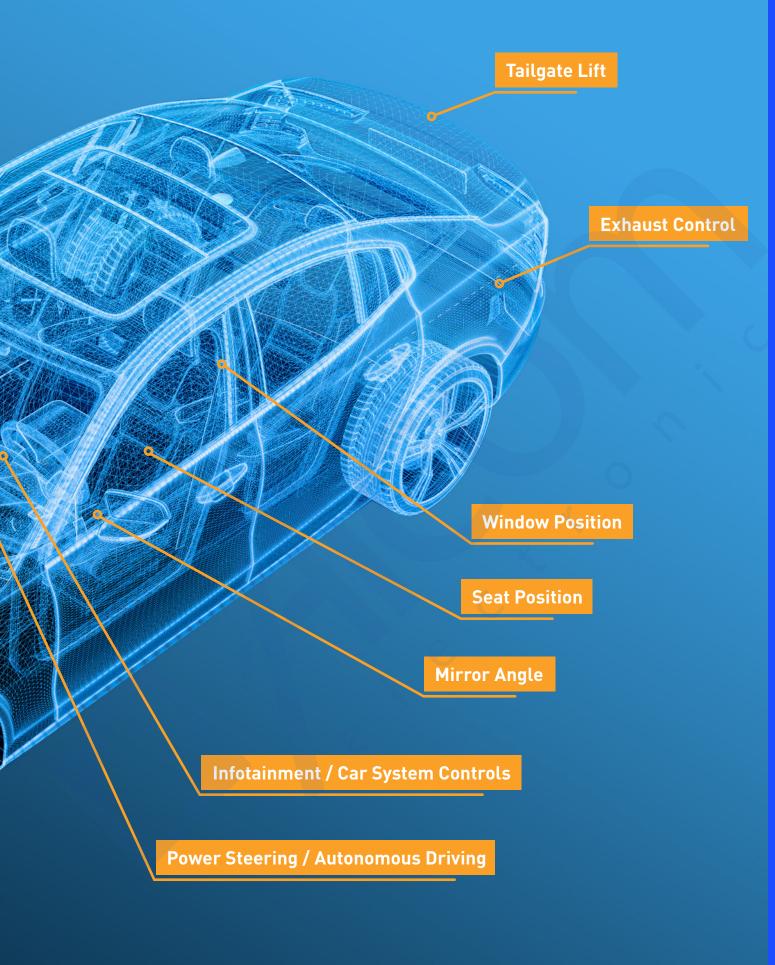
Figure 3: High-Voltage Isolation in Standard SOIC Package



# Sensors for Motor Position/Speed Control and Current Sensors



6



# **Body Electronics**



- » Retracting Door Handles
- » Tailgate Lifters
- » Suspension Sensors
- » Wiper Motors
- » Spoiler Actuation

# **Power Management**



- » Precision, High-Current Sensing and Control:
  - Wallbox Chargers
  - Qi Chargers
  - Power Monitoring Systems

# **Thermal Management**



- » Fluid Pumps
- » Air-Grill Shutters
- » Cooling Fan Modules

# **Interior Cabin Control and Car Audio**



- » Contactless Infotainment Consoles
- » Audio Amplifier Current Sensing
- » Contactless Gearshift Control
- » Seat Position Motor Control
- » Sunroof Motor Control

# **Power Steering**

#### Product Highlight

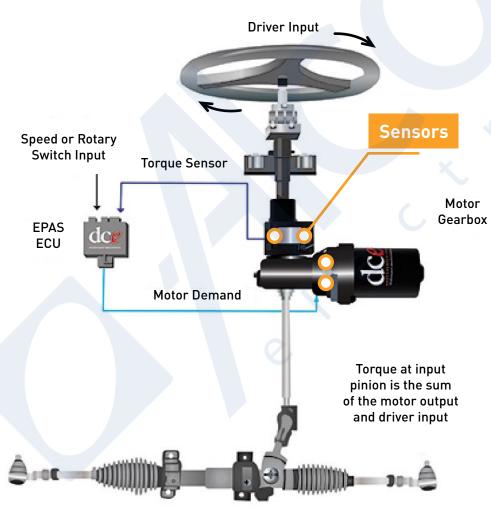
## **Replace Optical Sensors in Automotive Power-Assisted Steering (PAS)**

#### MAQ430 and MAQ473

- Motion Control and Position Sensing »
- Cost-Effective, Contactless Alternative to Optical Sensing **》**
- AEC-Q100 Grade 1 Qualified **»**
- Wide Operating Temperature Range: -40°C to +150°C **»**

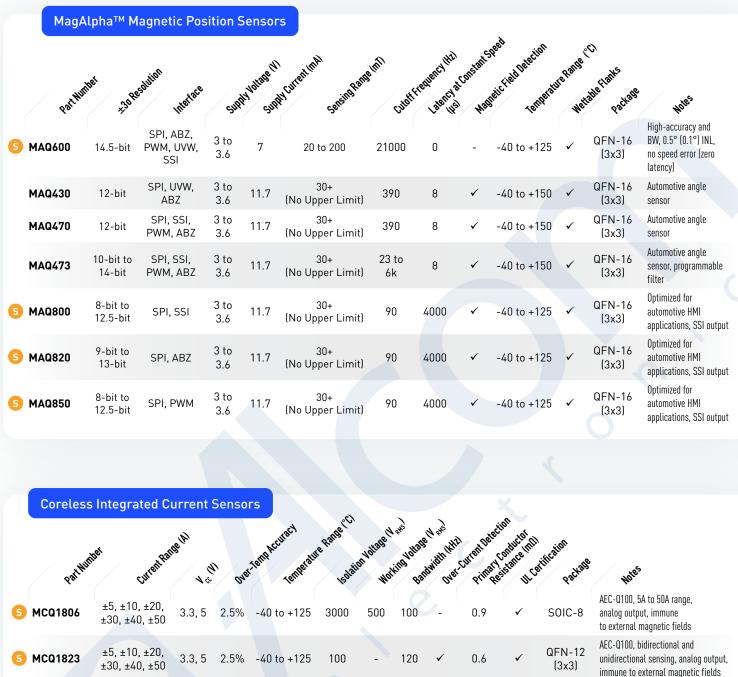
#### Simple to Use:

- No Calibration »
- Simple Field Diagnostics **»** 
  - Magnet Presence and Distance Detection



# AUTOMOTIVE

#### **AUTOMOTIVE PRODUCT SELECTOR GUIDE**





# **INDUSTRIAL BUILDING &** FACTORY AUTOMATION

# **Safety & Security**



- **Access Control** >>
- **Automated Doors** >>
- Smart Door Locks >>
- **Elevators and Escalators** >>
- **Fire Prevention** >>

# **Power Management**



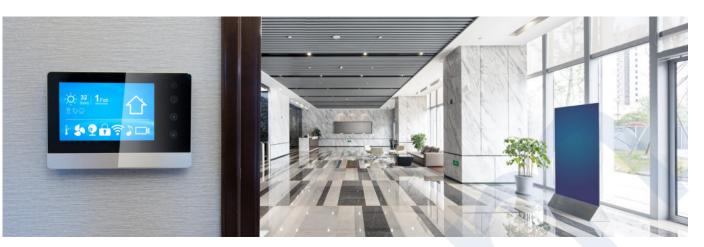
- » Solar Inverters
- » Power Monitoring
- » Power Access
- » Light Monitoring

# **Thermal Management**



- » Cooling
- » Fluid Pumps
- » Valve Control

# **Climate & Energy Efficiency**



- » Shutters and Blinds
- » HVAC Compressors, Blowers, Flow Control
- » Climate Control Thermostat

#### Product Highlight

#### **Smart Shades**

#### MA732, MA330, MA735, MA736, MA782

- » Motor Commutation and/or Position Feedback
- » Provides Absolute Feedback
- » Operates with a Low-Cost Magnet
- » Works with All Types of Motors
- » Can Be Operated at Side-Shaft or End-of-Shaft Locations
- » Ideal for Space-Constrained Applications
  - MA735, MA736, MA782: UTQFN (2mmx2mm) Package
- » MA782 Is Ideal for Battery-Powered Applications
  - Includes Wake-Up on Angle Detection
  - 0.5µA Standby Current



# **Industrial Automation**



#### Product Highlight

# **Precision Robotic Joint Control**

#### MA600

- 0.5° INL over Temp »
- <0.1° INL after User Calibration with On-Chip **》** 32-Point Lookup Table
- 11-Bit to 15-Bit Low Latency Resolution **»**
- 21kHz Bandwidth **»**
- Zero Latency to Minimize Speed Errors **»**
- No Calibration Required **»**

#### Cost-Effective Solution for Managing:

- High-Speed Torque »
- Position »
- Speed Control »



# MEDICAL TECHNOLOGY

 $\odot$ 

# **Lab Automation**



- » Robot Control
- » Probe Processing
- » Pump Motor Control

# **Surgical Robotics**



- » Automated and Remote Surgical Robots
- » Dental Processing

#### Product Highlight

# **Surgical Robotics**

#### MA600

- » 0.5° INL over Temp
- > <0.1° INL after User Calibration with On-Chip 32-Point Lookup Table
- » 11-Bit to 15-Bit Low Latency Resolution
- » 21kHz Bandwidth
- » Zero Latency to Minimize Speed Errors
- » No Calibration Required

#### Cost-Effective Solution for Managing:

- » High-Speed Torque
- » Position
- » Speed Control



# **Automated Motorized Equipment**



- » Ventilators and Respirators
- » Insulin and Fluid Pumps
- » Medical Beds

#### Product Highlight

#### **Hospital Beds**

#### MA732, MA735, MA736

- » Hospital Bed Comfort Controls and Locomotion Assist Motors
- » Absolute Position Feedback Control
- » 14-Bit Resolution
- » Ideal for Space-Constrained Applications
  - MA735, MA736: UTQFN (2mmx2mm) Package

#### Flexible Interface:

- » SPI for Digital Angle Readout and Configuration
- » Incremental 12-Bit ABZ Quad Encoder with Programmable PPT from 1 to 1024
- » 14-Bit PWM

# CONSUMER PRODUCTS

# Mobile Phones & Laptop Computers



- » Foldable Mobile Flip-Phone Angle Management
- » Foldable Tablet Angle Sensing
- » Precision Open/Close Angle Management

# **CONSUMER PRODUCTS**

#### Product Highlight

## **No-Bezel Laptops and Foldable Phones**

#### **MA782**

- Smallest Open/Close Detection Solution »
- Helps Minimize or Eliminate Bezel »
- Can Be Placed in the Folding Axis **»**
- » Smallest UTQFN (2mmx2mm) Package
- » Lowest Power: <0.5µA Standby Current</p>
- » Wake-On-Change Angle Detection
- » Very Small (<1mmx1mm) Magnet
- Provides Absolute Angle Output »



# **Battery-Powered Hand Tools**



#### Product Highlight

# **Power Tool BLDC Motor: Replace 3 Hall Switches** with 1 MagAlpha

#### **MA102**

- Eliminate Mechanical Alignment with Stator »
- Better Phase Alignment = Higher Torque and **»** Improved Efficiency
- Reduce Part Count by Up to 70% **»**
- Reduce PCB Size by Up to 70% **》**
- » Increase Mechanical Flexibility
- » UVW Output Means No Firmware Change
- Wide -40°C to +125°C Operating Temp Range »



Before

After Reduce PCB Size by Up to 70%

20

# E-Bikes & Scooters



- BLDC Motors Smaller, Lighter, Increased Reliability >>
- **Enables Highest Power Density** >>
- Provides Absolute Angle, Position, and Torque >>

#### Flexible Interface:

- **SPI Commutation for UVW Commutation** >>
- ABZ Speed Control **>>**

#### Product Highlight

# E-Bike Ultra-Small BLDC Motors

#### MA302

- Speed, Torque, and Absolute Position Control »
- Smallest QFN (3mmx3mm) Package »
- No Customer Calibration Required »
- **Factory Calibrated »**
- On-Chip Non-Volatile Memory (NVM) »
- Wide -40°C to +125°C Operating Temp Range **»**
- Flexible Interface »
  - -SPI for Digital Angle Readout and Sensor Configuration
  - ABZ/UVW for Motor Control, Commutation, and Incremental Output
  - No Firmware Changes Required when Replacing Optical Encoders; ABZ Output is Compatible with **Optical Outputs**



#### **COMPREHENSIVE PRODUCT SELECTOR GUIDE**

	CORELESS INTEGRATED CURRENT SENSORS												
	Parthumbe	Current Party	14 14 14	Dver terms	acit Temperaur	Range <sup>®CU</sup>	Hotage We	votage IV and Notage IV and Bandwidt	a WHILL OVER-CUT	ent Deection Primary Co	and the state of t	pathage	Holes
6	MCS1805	±5, ±10, ±20, ±30, ±40, ±50	3.3, 5	2.5%	-40 to +125	3000	500	120	√	0.9	Pending	SOIC-8	Coreless, 5A to 50A range, analog output, immune to external magnetic fields
N	MCS1806	±5, ±10, ±20, ±30, ±40, ±50	3.3, 5	2.5%	-40 to +125	3000	500	100	-	0.9	*	SOIC-8	Coreless, 5A to 50A range, analog output, immune to external magnetic fields
N	MCQ1806	±5, ±10, ±20, ±30, ±40, ±50	3.3, 5	2.5%	-40 to +125	3000	500	100	-	0.9	✓	SOIC-8	AECO-100, coreless, 5A to 50A range, analog output, immune to external magnetic fields
N	MCS1823	±5, ±10, ±20, ±30, ±40, ±50	3.3, 5	2.5%	-40 to +125	100	N/A	120	*	0.6	•	QFN-12 (3x3)	Bidirectional and unidirectional sensing, analog output, immune to external magnetic fields
5	MCQ1823	±5, ±10, ±20, ±30, ±40, ±50	3.3, 5	2.5%	-40 to +125	100	N/A	120	✓	0.6	*	QFN-12 (3x3)	AEC-0100, 5A to 50A range, analog output, immune to external magnetic fields
	MCS1800	±12.5, ±25	3.3	3%	-40 to +125	1000	200	100	-	1.2	ζ-	SOIC-8	Analog output, immune to external magnetic fields
	MCS1801	±12.5, ±25	5	3%	-40 to +125	1000	200	100	- ×	1.2	-	SOIC-8	Analog output, immune to external magnetic fields
	MCS1802	±5, ±10, ±20, ±30, ±40, ±50	3.3	2.5%	-40 to +125	2200	250	100	<b>/</b> -	0.9	√	SOIC-8	Analog output, immune to external magnetic fields
	MCS1803	±5, ±10, ±20, ±30, ±40, ±50	5	2.5%	-40 to +125	2200	250	100	-	0.9	$\checkmark$	SOIC-8	Analog output, immune to external magnetic fields

POSITION SENSO	R MAGNETS									
Pathinte	Wagnetitatio	n Gennetri	Hasia	00 <sup>11</sup>	nni D'	inni he	ight Immi	iap Min Inf	a Max Inni Rat	ind tolerance (mm) wees
MAG10-2C-30.25	Diametrical	Cylinder	NdFeB, Grade N35SH	3	-	2.5	0	2	0.1	
MAG10-2C-40.25	Diametrical	Cylinder	NdFeB, Grade N35SH	4	-	2.5	0	2.6	0.2	Standard-size, cost- effective
MAG10-2C-50.25	Diametrical	Cylinder	NdFeB, Grade N35SH	5	-	2.5	0	3.1	0.2	Standard-size, cost- effective
MAG10-2C-60.25	Diametrical	Cylinder	NdFeB, Grade N35SH	6	-	2.5	0	3.6	0.3	-
MAG10-2C-80.25	Diametrical	Cylinder	NdFeB, Grade N35SH	8	-	2.5	0	4.5	0.4	-
MAG10-2R-50.12.25	Diametrical	Ring	NdFeB, Grade N35SH	5	1.25	2.5	1	1.4	0.4	Accurate application
MAG10-2R-60.15.25	Diametrical	Ring	NdFeB, Grade N35SH	6	1.5	2.5	1.3	1.6	0.6	Accurate application
MAG10-2R-80.20.25	Diametrical	Ring	NdFeB, Grade N35SH	8	2	2.5	2	2.5	0.8	Accurate application
MAG10-2B-40.25	Axial	Half-Cylinder	NdFeB, Grade N35SH	4	-	2.5	0	2.1	<0.1	Low field emission
MAG10-2B-50.25	Axial	Half-Cylinder	NdFeB, Grade N35SH	5	-	2.5	0	2.7	<0.1	Low field emission
MAG10-2B-60.25	Axial	Half-Cylinder	NdFeB, Grade N35SH	6	-	2.5	0	3.2	<0.1	Low field emission
MAG10-2B-80.25	Axial	Half-Cylinder	NdFeB, Grade N35SH	8	-	2.5	0	4.2	0.1	Low field emission

MagVector<sup>™</sup> 3D Magnetic Position Sensors



MagAlpha<sup>™</sup> Magnetic Position Sensors

					, <sup>ti</sup>	a ma	mil	ney HAZ	statt	angeci	
	Pathu	inper *30 Pe	solution Interface	SUP	AN Voltage	y Currentine Sensing F	ange Cutoff	requency little	ups Temper	Jue Pare Ci Pattage	Holes
M	A102	12-bit	SPI, UVW	3 to 3.6	11.7	30+ (No Upper Limit)	390	8	-40 to +125	QFN-16 (3x3)	Motor commutation angle sensor, UVW multi-pole pair, differential outputs
м	A302	12-bit	SPI, UVW, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	390	8	-40 to +125	QFN-16 (3x3)	Motor commutation angle sensor, 12-bit SPI output, ABZ & UVW incremental outputs
M	A310	12-bit	SPI, UVW, ABZ	3 to 3.6	11.7	15+ (No Upper Limit)	93	8	-40 to +125	QFN-16 (3x3)	Motor commutation angle sensor, 12-bit SPI output, low magnetic field
M	A330	10-bit to 14- bit	SPI, UVW, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	23 to 6k	8	-40 to +125	QFN-16 (3x3)	Motor commutation angle sensor, up to 14-bit SPI output, programmable filter
M	4702	12-bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	390	8	-40 to +125	QFN-16 (3x3)	12-bit SPI output, ABZ incremental & PWM outputs
м	A704	10-bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	2970	8	-40 to +125	QFN-16 (3x3)	12-bit SPI output, high BW, ABZ incremental & PWM outputs
M	4710	12-bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	15+ (No Upper Limit)	93	8	-40 to +125	QFN-16 (3x3)	12-bit SPI output, low magnetic field, ABZ incremental & PWM outputs
м	4730	14-bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	40+ (No Upper Limit)	23	8	-40 to +125	QFN-16 (3x3)	14-bit SPI output, ABZ incremental & PWM outputs
M	4732	10-bit to 14- bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	23 to 6k	8	-40 to +125	QFN-16 (3x3)	Programmable filter, ABZ incremental & PWM outputs
M	A734	8-bit to 12.5- bit	SPI	3 to 3.6	11	30+ (No Upper Limit)	95, 380, 95000	3	-40 to +125	QFN-16 (3x3)	Programmable filter, low latency
N M/	A735	9-bit to 13-bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	40+ (No Upper Limit)	23 to 6k	8	-40 to +125	UTQFN-14 (2x2)	Ultra-small footprint, programmable filter, ABZ incremental & PWM outputs
N M/	A736	8-bit to 12.5- bit	SPI	3 to 3.6	11	30+ (No Upper Limit)	95, 380, 95000	3	-40 to +125	UTQFN-14 (2x2)	Ultra-small footprint, programmable filter, low latency
M	A800	8-bit	SPI, SSI	3 to 3.6	11.7	30+ (No Upper Limit)	90	4000	-40 to +125	QFN-16 (3x3)	Optimized for HMI applications
M	A820	8-bit	SPI, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	90	4000	-40 to +125	QFN-16 (3x3)	Optimized for HMI applications
M	A850	8-bit	SPI, PWM	3 to 3.6	11.7	30+ (No Upper Limit)	90	4000	-40 to +125	QFN-16 (3x3)	Optimized for HMI applications
N M/	A600	15-bit	SPI, ABZ, PWM, UVW, SSI	3 to 3.6	7	10 to 150	21000	0	-40 to +125	QFN-16 (3x3)	High accuracy & BW, 0.5° (0.1°) INL, no speed error (zero latency)
<b>N</b> М/	AQ600	15-bit	SPI, ABZ, PWM, UVW, SSI	3 to 3.6	7	10 to 150	21000	0	-40 to +125	QFN-16 (3x3)	High accuracy & BW, 0.5° (0.1°) INL, no speed error (zero latency), wettable flanks

**COMPREHENSIVE PRODUCT SELECTOR GUIDE** 

MagAlpha<sup>™</sup> Magnetic Position Sensors

			ion		Rel I	A milmal	relnil	encytha	mstant	Bangel	
	Parthu	inter +30 Ref	solution Interface	SUL	ally votrage	W <sup>Current</sup> m <sup>A</sup> Sensing <sup>F</sup>	ans Cuto	I Frequency Hall	onstant d US Temper	HUP PORF CU Pattage	Hotes
	MA780	8-bit to 12-bit	SPI	3 to 3.6	0.5µA to 10	30+ (No Upper Limit)	5 to 160k	4 to 4000	-40 to +125	QFN-16 (3x3)	Optimized for low-power, integrated wake-up and IRQ
	MA782	8-bit to 12-bit	SPI	3 to 3.6	0.5µA to 10	30+ (No Upper Limit)	5 to 160k	4 to 4000	-40 to +125	UTQFN-14 (2x2)	Ultra-small footprint, integrated wake-up and IRQ
	MAQ430	12-bit	SPI, UVW, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	390	8	-40 to +150	QFN-16 (3x3)	Automotive angle sensor, wettable flanks
	MAQ470	12-bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	390	8	-40 to +150	QFN-16 (3x3)	Automotive angle sensor, wettable flanks
	MAQ473	10-bit to 14- bit	SPI, SSI, PWM, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	23 to 6k	8	-40 to +150	QFN-16 (3x3)	Automotive angle sensor, programmable filter, wettable flanks
S	MAQ800	8-bit to 12.5- bit	SPI, SSI	3 to 3.6	11.7	30+ (No Upper Limit)	90	4000	-40 to +125	QFN-16 (3x3)	Optimized for automotive HMI applications, SSI output, wettable flanks
S	MAQ820	9-bit to 13-bit	SPI, ABZ	3 to 3.6	11.7	30+ (No Upper Limit)	90	4000	-40 to +125	QFN-16 (3x3)	Optimized for automotive HMI applications, SSI output, wettable flanks
5	MAQ850	8-bit to 12.5- bit	SPI, PWM	3 to 3.6	11.7	30+ (No Upper Limit)	90	4000	-40 to +125	QFN-16 (3x3)	Optimized for automotive HMI applications, SSI output, wettable flanks